## Logistic Regression

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## Problem Setup

## Classification Technique



Oranges
$\square$ Tomatoes

## Classification Technique



## Classification Technique



Aim: Probability(Tomatoes | Radius) ? or

## Classification Technique



Aim: Probability(Tomatoes | Radius) ? or
More generally, $\mathrm{P}(y=1 \mid X=x)$ ?

## Idea: Use Linear Regression



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Generally,

$$
P(y=1 \mid x)=X \theta
$$

## Idea: Use Linear Regression

Prediction:
If $\theta_{0}+\theta_{1} \times$ Radius $>0.5 \rightarrow$ Orange Else $\rightarrow$ Tomato
Problem:
Range of $X \theta$ is $(-\infty, \infty)$
But $P(y=1 \mid \ldots) \in[0,1]$

## Idea: Use Linear Regression



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Linear regression for classification gives a poor prediction!

## Ideal boundary



- Have a decision function similar to the above (but not so sharp and discontinuous)


## Ideal boundary



- Have a decision function similar to the above (but not so sharp and discontinuous)
- Aim: use linear regression still!


## Idea: Use Linear Regression



Question. Can we still use Linear Regression?
Answer. Yes! Transform $\hat{y} \rightarrow[0,1]$

## Logistic/Sigmoid function

## Logistic / Sigmoid Function

$$
\begin{aligned}
& \hat{y} \in(-\infty, \infty) \\
& \phi=\text { Sigmoid / Logistic Function }(\sigma) \\
& \phi(\hat{y}) \in[0,1]
\end{aligned}
$$

$$
\sigma(z)=\frac{1}{1+e^{-z}}
$$



$$
z \rightarrow \infty
$$

$$
\begin{aligned}
& z \rightarrow \infty \\
& \sigma(z) \rightarrow 1
\end{aligned}
$$

# Logistic / Sigmoid Function 

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$$

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\begin{aligned}
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& \sigma(z) \rightarrow 0 \\
& z=0
\end{aligned}
$$

# Logistic / Sigmoid Function 

$$
\begin{aligned}
& z \rightarrow \infty \\
& \sigma(z) \rightarrow 1 \\
& z \rightarrow-\infty \\
& \sigma(z) \rightarrow 0 \\
& z=0 \\
& \sigma(z)=0.5
\end{aligned}
$$

## Logistic / Sigmoid Function

Question. Could you use some other transformation $(\phi)$ of $\hat{y}$ s.t.

$$
\phi(\hat{y}) \in[0,1]
$$

Yes! But Logistic Regression works.

## Logistic / Sigmoid Function

$$
P(y=1 \mid X)=\sigma(X \theta)=\frac{1}{1+e^{-X \theta}}
$$

Q. Write $X \theta$ in a more convenient form (as $P(y=1 \mid X)$, $P(y=0 \mid X))$

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$$
\begin{aligned}
& P(y=0 \mid X)=1-P(y=1 \mid X)=1-\frac{1}{1+e^{-X \theta}}=\frac{e^{-X \theta}}{1+e^{-X \theta}} \\
& \therefore \frac{P(y=1 \mid X)}{1-P(y=1 \mid X)}=e^{X \theta} \Longrightarrow X \theta=\log \frac{P(y=1 \mid X)}{1-P(y=1 \mid X)}
\end{aligned}
$$

## Odds (Used in betting)

$$
\frac{P(\text { win })}{P(\text { loss })}
$$

Here,

$$
O d d s=\frac{P(y=1)}{P(y=0)}
$$

$$
\log \text {-odds }=\log \frac{P(y=1)}{P(y=0)}=X \theta
$$

## Logistic Regression

Q. What is decision boundary for Logistic Regression?

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Decision Boundary: $P(y=1 \mid X)=P(y=0 \mid X)$

$$
\begin{aligned}
& \text { or } \frac{1}{1+e^{-X \theta}}=\frac{e^{-X \theta}}{1+e^{-X \theta}} \\
& \text { or } e^{X \theta}=1
\end{aligned}
$$

$$
\text { or } X \theta=0
$$

## Learning Parameters

Could we use cost function as:

$$
\begin{gathered}
J(\theta)=\sum\left(y_{i}-\hat{y}_{i}\right)^{2} \\
\hat{y}_{i}=\sigma(X \theta)
\end{gathered}
$$

Answer: No (Non-Convex)
(See Jupyter Notebook)

Deriving Cost Function via
Maximum Likelihood Estimation

## Cost function convexity



RMSE surface plot


## Learning Parameters

Likelihood $=P(D \mid \theta)$
$P(y \mid X, \theta)=\prod_{i=1}^{n} P\left(y_{i} \mid x_{i}, \theta\right)$
where $\mathrm{y}=0$ or 1

## Learning Parameters

Likelihood $=P(D \mid \theta)$

$$
\begin{aligned}
P(y \mid X, \theta) & =\prod_{i=1}^{n} P\left(y_{i} \mid x_{i}, \theta\right) \\
& =\prod_{i=1}^{n}\left\{\frac{1}{1+e^{-x_{i}^{T} \theta}}\right\}^{y_{i}}\left\{1-\frac{1}{1+e^{-x_{i}^{T} \theta}}\right\}^{1-y_{i}}
\end{aligned}
$$

[Above: Similar to $P(D \mid \theta)$ for Linear Regression; Difference Bernoulli instead of Gaussian]

$$
\begin{aligned}
-\log P(y \mid X, \theta) & =\text { Negative Log Likelihood } \\
& =\text { Cost function will be minimising } \\
& =J(\theta)
\end{aligned}
$$

## Aside on Bernoulli Likelihood

- Assume you have a coin and flip it ten times and get $(\mathrm{H}, \mathrm{H}$, T, T, T, H, H, T, T, T).


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- What is $p(H)$ ?


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- Answer 1: Probability defined as a measure of long running frequencies


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- Answer 2: What is likelihood of seeing the above sequence when the $\mathrm{p}($ Head $)=\theta$ ?


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- Answer 1: Probability defined as a measure of long running frequencies
- Answer 2: What is likelihood of seeing the above sequence when the $\mathrm{p}($ Head $)=\theta$ ?
- Idea find MLE estimate for $\theta$


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- Verify the above: if $x=0$ (Tails), $P\left(D_{1}=x \mid \theta\right)=1-\theta$ and if $x=1$ (Heads), $P\left(D_{1}=x \mid \theta\right)=\theta$


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- Log-likelihood $=\mathcal{L L}(\theta)=n_{h} \log (\theta)+n_{t} \log (1-\theta)$


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- $P\left(D_{1}, D_{2}, \ldots, D_{n} \mid \theta\right)=\theta^{n_{h}}(1-\theta)^{n_{t}}$
- Log-likelihood $=\mathcal{L L}(\theta)=n_{h} \log (\theta)+n_{t} \log (1-\theta)$
- $\frac{\partial \mathcal{L L}(\theta)}{\partial \theta}=0 \Longrightarrow \frac{n_{h}}{\theta}+\frac{n_{t}}{1-\theta}=0 \Longrightarrow \theta_{M L E}=\frac{n_{h}}{n_{h}+n_{t}}$


## Cross Entropy Cost Function

## Learning Parameters

$$
\begin{aligned}
& J(\theta)=-\log \left\{\prod_{i=1}^{n}\left\{\frac{1}{1+e^{-x_{i}^{T}}}\right\}^{y_{i}}\left\{1-\frac{1}{1+e^{-x_{i}^{\top} \theta}}\right\}^{1-y_{i}}\right\} \\
& J(\theta)=-\left\{\sum_{i=1}^{n} y_{i} \log \left(\sigma_{\theta}\left(x_{i}\right)\right)+\left(1-y_{i}\right) \log \left(1-\sigma_{\theta}\left(x_{i}\right)\right)\right\}
\end{aligned}
$$

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\end{aligned}
$$

This cost function is called cross-entropy.

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& J(\theta)=-\left\{\sum_{i=1}^{n} y_{i} \log \left(\sigma_{\theta}\left(x_{i}\right)\right)+\left(1-y_{i}\right) \log \left(1-\sigma_{\theta}\left(x_{i}\right)\right)\right\}
\end{aligned}
$$

This cost function is called cross-entropy.
Why?

## Interpretation of Cross-Entropy Cost Function

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$$
J(\theta)=-y_{i} \log \hat{y}_{i}-\left(1-y_{i}\right) \log \left(1-\hat{y}_{i}\right)
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## Interpretation of Cross-Entropy Cost Function

What is the interpretation of the cost function?
Let us try to write the cost function for a single example:

$$
J(\theta)=-y_{i} \log \hat{y}_{i}-\left(1-y_{i}\right) \log \left(1-\hat{y}_{i}\right)
$$

First, assume $y_{i}$ is 0 , then if $\hat{y}_{i}$ is 0 , the loss is 0 ; but, if $\hat{y}_{i}$ is 1 , the loss tends towards infinity!


Notebook: logits-usage

## Interpretation of Cross-Entropy Cost Function

What is the interpretation of the cost function?

$$
J(\theta)=-y_{i} \log \hat{y}_{i}-\left(1-y_{i}\right) \log \left(1-\hat{y}_{i}\right)
$$

## Interpretation of Cross-Entropy Cost Function

What is the interpretation of the cost function?

$$
J(\theta)=-y_{i} \log \hat{y}_{i}-\left(1-y_{i}\right) \log \left(1-\hat{y}_{i}\right)
$$

Now, assume $y_{i}$ is 1 , then if $\hat{y}_{i}$ is 0 , the loss is huge; but, if $\hat{y}_{i}$ is 1 , the loss is zero!


## Cost function convexity



Cross-entropy surface plot


## Learning Parameters

$$
\begin{aligned}
\frac{\partial J(\theta)}{\partial \theta_{j}} & =-\frac{\partial}{\partial \theta_{j}}\left\{\sum_{i=1}^{n} y_{i} \log \left(\sigma_{\theta}\left(x_{i}\right)\right)+\left(1-y_{i}\right) \log \left(1-\sigma_{\theta}\left(x_{i}\right)\right)\right\} \\
& =-\sum_{i=1}^{n}\left[y_{i} \frac{\partial}{\partial \theta_{j}} \log \left(\sigma_{\theta}\left(x_{i}\right)\right)+\left(1-y_{i}\right) \frac{\partial}{\partial \theta_{j}} \log \left(1-\sigma_{\theta}\left(x_{i}\right)\right)\right]
\end{aligned}
$$

## Learning Parameters

$$
\begin{gather*}
\frac{\partial J(\theta)}{\partial \theta_{j}}=-\sum_{i=1}^{n}\left[y_{i} \frac{\partial}{\partial \theta_{j}} \log \left(\sigma_{\theta}\left(x_{i}\right)\right)+\left(1-y_{i}\right) \frac{\partial}{\partial \theta_{j}} \log \left(1-\sigma_{\theta}\left(x_{i}\right)\right)\right] \\
\quad=-\sum_{i=1}^{n}\left[\frac{y_{i}}{\sigma_{\theta}\left(x_{i}\right)} \frac{\partial}{\partial \theta_{j}} \sigma_{\theta}\left(x_{i}\right)+\frac{1-y_{i}}{1-\sigma_{\theta}\left(x_{i}\right)} \frac{\partial}{\partial \theta_{j}}\left(1-\sigma_{\theta}\left(x_{i}\right)\right)\right] \tag{1}
\end{gather*}
$$

Aside:

$$
\begin{aligned}
\frac{\partial}{\partial z} \sigma(z) & =\frac{\partial}{\partial z} \frac{1}{1+e^{-z}}=-\left(1+e^{-z}\right)^{-2} \frac{\partial}{\partial z}\left(1+e^{-z}\right) \\
=\frac{e^{-z}}{\left(1+e^{-z}\right)^{2}}=\left(\frac{1}{1+e^{-z}}\right)\left(\frac{e^{-z}}{1+e^{-z}}\right) & =\sigma(z)\left\{\frac{1+e^{-z}}{1+e^{-z}}-\frac{1}{1+e^{-z}}\right\} \\
& =\sigma(z)(1-\sigma(z))
\end{aligned}
$$

## Learning Parameters

Resuming from (1)

$$
\begin{gathered}
\frac{\partial J(\theta)}{\partial \theta_{j}}=-\sum_{i=1}^{n}\left[\frac{y_{i}}{\sigma_{\theta}\left(x_{i}\right)} \frac{\partial}{\partial \theta_{j}} \sigma_{\theta}\left(x_{i}\right)+\frac{1-y_{i}}{1-\sigma_{\theta}\left(x_{i}\right)} \frac{\partial}{\partial \theta_{j}}\left(1-\sigma_{\theta}\left(x_{i}\right)\right)\right] \\
=-\sum_{i=1}^{n}\left[\frac{y_{i} \sigma_{\theta}\left(x_{i}\right)}{\sigma_{\theta}\left(x_{i}\right)}\left(1-\sigma_{\theta}\left(x_{i}\right)\right) \frac{\partial}{\partial \theta_{j}}\left(x_{i} \theta\right)+\frac{1-y_{i}}{1-\sigma_{\theta}\left(x_{i}\right)}\left(1-\sigma_{\theta}\left(x_{i}\right)\right) \frac{\partial}{\partial \theta_{j}}\left(1-\sigma_{\theta}\left(x_{i}\right)\right)\right] \\
=-\sum_{i=1}^{n}\left[y_{i}\left(1-\sigma_{\theta}\left(x_{i}\right)\right) x_{i}^{j}-\left(1-y_{i}\right) \sigma_{\theta}\left(x_{i}\right) x_{i}^{j}\right] \\
=-\sum_{i=1}^{n}\left[\left(y_{i}-y_{i} \sigma_{\theta}\left(x_{i}\right)-\sigma_{\theta}\left(x_{i}\right)+y_{i} \sigma_{\theta}\left(x_{i}\right)\right) x_{i}^{j}\right] \\
=\sum_{i=1}^{n}\left[\sigma_{\theta}\left(x_{i}\right)-y_{i}\right] x_{i}^{j}
\end{gathered}
$$

## Learning Parameters

$$
\frac{\partial J(\theta)}{\theta_{j}}=\sum_{i=1}^{N}\left[\sigma_{\theta}\left(x_{i}\right)-y_{i}\right] x_{i}^{j}
$$

Now, just use Gradient Descent!

$$
\frac{\partial J(\theta)}{\partial \theta_{j}}=\sum_{i=1}^{N}\left(\hat{y}_{i}-y_{i}\right) x_{i}^{j}
$$

$$
\frac{\partial J(\theta)}{\partial \theta_{j}}=\sum_{i=1}^{N}\left(\hat{y}_{i}-y_{i}\right) x_{i}^{j}
$$

MATRIX $X$


$$
\frac{\partial J(\theta)}{\partial \theta_{j}}=\sum_{i=1}^{N}\left(\hat{y}_{i}-y_{i}\right) x_{i}^{j}
$$


column of $x$

$$
=x^{j}
$$

$$
\frac{\partial J(\theta)}{\partial \theta_{j}}=\sum_{i=1}^{N}\left(\hat{y}_{i}-y_{i}\right) x_{i}^{j}
$$


$j^{\text {n }}$ column of $x$

$$
=x^{j}
$$

$$
\frac{\partial J(\theta)}{\partial \theta_{j}}=\sum_{i=1}^{N}\left(\hat{y}_{i}-y_{i}\right) x_{i}^{j}
$$


$\int^{\text {h }}$ column of $x$

$$
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$$

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\frac{\partial J(\theta)}{\partial \theta_{j}}=\sum_{i=1}^{N}\left(\hat{y}_{i}-y_{i}\right) x_{i}^{j}
$$


$j^{\text {h }}$ column of $x$

$$
=x^{j}
$$

$$
\frac{\partial J(\theta)}{\partial \theta_{j}}=\sum_{i=1}^{N}\left(\hat{y}_{i}-y_{i}\right) x_{i}^{j}=x_{1 \times N}^{\top}(\hat{y}-y)
$$

Matelx $x$ gh column of $x$

$$
=x^{j}
$$

$$
\begin{aligned}
& \frac{\partial J(\theta)}{\partial \theta j}=\sum_{i=1}^{N}\left(\hat{y}_{i}-y_{i}\right) x_{i}^{j}=x_{1 \times N}^{j^{\top}}(\hat{y}-y) \\
& {\left[\begin{array}{c}
\frac{\partial J(\theta)}{\partial \theta_{1}} \\
\frac{\partial J(\theta)}{\partial \theta_{2}} \\
\vdots \\
\frac{\partial J(\theta)}{\partial \theta_{D}}
\end{array}\right]=\left(\begin{array}{c}
x^{\top}\left(y^{\top}-y\right) \\
x^{2^{\top}}(\hat{y}-y) \\
\vdots \\
\vdots \\
x^{\top}\left(y^{n}-y\right)
\end{array}\right)}
\end{aligned}
$$

$$
\begin{aligned}
& \frac{\partial J(\theta)}{\partial \theta_{j}}=\sum_{i=1}^{N}\left(\hat{y}_{i}-y_{i}\right) x_{i}^{j}=x_{1 \times N}^{\top}(\hat{y}-y) \\
& {\left[\begin{array}{c}
\frac{\partial J(\theta)}{\partial \theta_{1}} \\
\frac{\partial J(\theta)}{\partial \theta_{2}} \\
\vdots \\
\frac{\partial J(0)}{\partial \theta_{D}}
\end{array}\right]=\left(\begin{array}{c}
x^{\top}\left(y^{2}-y\right) \\
x^{2^{\top}}(\hat{y}-y) \\
\vdots \\
\vdots \\
x^{\top}\left(y^{n}-y\right)
\end{array}\right)=x^{\top}(\hat{y}-y)}
\end{aligned}
$$

## Logistic Regression with feature transformation



What happens if you apply logistic regression on the above data?

## Logistic Regression with feature transformation



Linear boundary will not be accurate here. What is the technical name of the problem?

## Logistic Regression with feature transformation



Linear boundary will not be accurate here. What is the technical name of the problem? Bias!

## Logistic Regression with feature transformation

$$
\phi(x)=\left[\begin{array}{c}
\phi_{0}(x) \\
\phi_{1}(x) \\
\vdots \\
\phi_{K-1}(x)
\end{array}\right]=\left[\begin{array}{c}
1 \\
x \\
x^{2} \\
x^{3} \\
\vdots \\
x^{K-1}
\end{array}\right] \in \mathbb{R}^{K}
$$

## Logistic Regression with feature transformation



Using $x_{1}^{2}, x_{2}^{2}$ as additional features, we are able to learn a more accurate classifier.

## Logistic Regression with feature transformation

How would you expect the probability contours look like?

## Logistic Regression with feature transformation

How would you expect the probability contours look like?


## Multi-Class Prediction



## Multi-Class Prediction



How would you learn a classifier? Or, how would you expect the classifier to learn decision boundaries?

## Multi-Class Prediction



## Multi-Class Prediction



1. Use one-vs.-all on Binary Logistic Regression
2. Use one-vs.-one on Binary Logistic Regression
3. Extend Binary Logistic Regression to Multi-Class Logistic Regression

## Multi-Class Prediction



## Multi-Class Prediction



1. Learn $\mathrm{P}($ setosa $($ class 1$))=\mathcal{F}\left(X \theta_{1}\right)$
2. $\mathrm{P}($ versicolor $($ class 2$))=\mathcal{F}\left(X \theta_{2}\right)$
3. $\mathrm{P}($ virginica $($ class 3$))=\mathcal{F}\left(X \theta_{3}\right)$
4. Goal: Learn $\theta_{i} \forall i \in\{1,2,3\}$
5. Question: What could be an $\mathcal{F}$ ?

## Multi-Class Prediction



## Multi-Class Prediction



1. Question: What could be an $\mathcal{F}$ ?
2. Property: $\sum_{i=1}^{3} \mathcal{F}\left(X \theta_{i}\right)=1$
3. Also $\mathcal{F}(z) \in[0,1]$
4. Also, $\mathcal{F}(z)$ has squashing proprties: $R \mapsto[0,1]$

## Softmax

$$
\begin{gathered}
Z \in \mathbb{R}^{d} \\
\mathcal{F}\left(z_{i}\right)=\frac{e^{z_{i}}}{\sum_{i=1}^{d} e^{z_{i}}} \\
\therefore \sum \mathcal{F}\left(z_{i}\right)=1
\end{gathered}
$$

$\mathcal{F}\left(z_{i}\right)$ refers to probability of class $\underline{i}$

## Softmax for Multi-Class Logistic Regression

$$
\begin{gathered}
k=\{1, \ldots, k\} \text { classes } \\
\theta=\left[\begin{array}{cccc}
\vdots & \vdots & \vdots & \vdots \\
\theta_{1} & \theta_{2} & \cdots & \theta_{k} \\
\vdots & \vdots & \vdots & \vdots
\end{array}\right] \\
P(y=k \mid X, \theta)=\frac{e^{X \theta_{k}}}{\sum_{k=1}^{K} e^{X \theta_{k}}}
\end{gathered}
$$

## Softmax for Multi-Class Logistic Regression

For $\mathrm{K}=2$ classes,

$$
\begin{gathered}
P(y=k \mid X, \theta)=\frac{e^{X \theta_{k}}}{\sum_{k=1}^{K} e^{X \theta_{k}}} \\
P(y=0 \mid X, \theta)=\frac{e^{X \theta_{0}}}{e^{X \theta_{0}}+e^{X \theta_{1}}} \\
P(y=1 \mid X, \theta)=\frac{e^{X \theta_{1}}}{e^{X \theta_{0}}+e^{X \theta_{1}}}=\frac{e^{X \theta_{1}}}{e^{X \theta_{1}}\left\{1+e^{X\left(\theta_{0}-\theta_{1}\right)}\right\}} \\
=\frac{1}{1+e^{-X \theta^{\prime}}} \\
=\text { Sigmoid! }
\end{gathered}
$$

## Multi-Class Logistic Regression Cost

Assume our prediction and ground truth for the three classes for $i^{\text {th }}$ point is:

$$
\begin{gathered}
\hat{y}_{i}=\left[\begin{array}{l}
0.1 \\
0.8 \\
0.1
\end{array}\right]=\left[\begin{array}{l}
\hat{y}_{i}^{1} \\
\hat{y}_{i}^{2} \\
\hat{y}_{i}^{3}
\end{array}\right] \\
y_{i}=\left[\begin{array}{l}
0 \\
1 \\
0
\end{array}\right]=\left[\begin{array}{l}
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meaning the true class is Class \#2

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$=-(0 \times \log (0.1)+1 \times \log (0.8)+0 \times \log (0.1))$

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Tends to zero

## Multi-Class Logistic Regression Cost

Assume our prediction and ground truth for the three classes for $i^{\text {th }}$ point is:

$$
\begin{gathered}
\hat{y}_{i}=\left[\begin{array}{l}
0.3 \\
0.4 \\
0.3
\end{array}\right]=\left[\begin{array}{l}
\hat{y}_{i}^{1} \\
\hat{y}_{i}^{2} \\
\hat{y}_{i}^{3}
\end{array}\right] \\
y_{i}=\left[\begin{array}{l}
0 \\
1 \\
0
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\end{array}\right] \\
y_{i}=\left[\begin{array}{l}
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1 \\
0
\end{array}\right]=\left[\begin{array}{l}
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meaning the true class is Class \#2
Let us calculate $-\sum_{k=1}^{3} y_{i}^{k} \log \hat{y}_{i}^{k}$
$=-(0 \times \log (0.1)+1 \times \log (0.4)+0 \times \log (0.1))$
High number! Huge penalty for misclassification!

## Multi-Class Logistic Regression Cost

For 2 class we had:

$$
J(\theta)=-\left\{\sum_{i=1}^{n} y_{i} \log \left(\sigma_{\theta}\left(x_{i}\right)\right)+\left(1-y_{i}\right) \log \left(1-\sigma_{\theta}\left(x_{i}\right)\right)\right\}
$$

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$$

More generally,

## Multi-Class Logistic Regression Cost

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More generally,

$$
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$$

More generally,

$$
\begin{aligned}
& J(\theta)=-\left\{\sum_{i=1}^{n} y_{i} \log \left(\hat{y}_{i}\right)+\left(1-y_{i}\right) \log \left(1-\hat{y}_{i}\right)\right\} \\
& J(\theta)=-\left\{\sum_{i=1}^{n} y_{i} \log \left(\hat{y}_{i}\right)+\left(1-y_{i}\right) \log \left(1-\hat{y}_{i}\right)\right\}
\end{aligned}
$$

Extend to K-class:

$$
J(\theta)=-\left\{\sum_{i=1}^{n} \sum_{k=1}^{k} y_{i}^{k} \log \left(\hat{y}_{i}^{k}\right)\right\}
$$

## Multi-Class Logistic Regression Cost

Now:

$$
\frac{\partial J(\theta)}{\partial \theta_{k}}=\sum_{i=1}^{n}\left[x_{i}\left\{I\left(y_{i}=k\right)-P\left(y_{i}=k \mid x_{i}, \theta\right)\right\}\right]
$$

## Hessian Matrix

The Hessian matrix of $f\left(\right.$.) with respect to $\theta$, written $\nabla_{\theta}^{2} f(\theta)$ or simply as $\mathbb{H}$, is the $d \times d$ matrix of partial derivatives,

$$
\nabla_{\theta}^{2} f(\theta)=\left[\begin{array}{cccc}
\frac{\partial^{2} f(\theta)}{\frac{\partial \theta}{2}} & \frac{\partial^{2} f(\theta)}{\partial \theta^{2} \partial \theta^{2}} & \ldots & \frac{\partial^{2} f(\theta)}{\partial \theta^{2} \partial \theta_{n}} \\
\frac{\partial^{2} f(\theta)}{\partial \theta_{2} \partial \theta_{1}} & \frac{\partial^{2} f(\theta)}{\partial \theta_{2}^{2}} & \ldots & \frac{\partial^{2} f(\theta)}{\partial \theta_{2} \partial \theta_{n}} \\
\ldots & \ldots & \ldots & \ldots \\
\ldots & \ldots & \ldots & \ldots \\
\frac{\partial^{2} f(\theta)}{\partial \theta_{n} \partial \theta_{1}} & \frac{\partial^{2} f(\theta)}{\partial \theta_{n} \partial \theta_{2}} & \ldots & \frac{\partial^{2} f(\theta)}{\partial \theta_{n}^{2}}
\end{array}\right]
$$

## Newton's Algorithm

The most basic second-order optimization algorithm is Newton's algorithm, which consists of updates of the form,

$$
\theta_{k+1}=\theta_{k}-\mathbb{H}_{k}^{1} g_{k}
$$

where $g_{k}$ is the gradient at step $k$. This algorithm is derived by making a second-order Taylor series approximation of $f(\theta)$ around $\theta_{k}$ :

$$
f_{\text {quad }}(\theta)=f\left(\theta_{k}\right)+g_{k}^{T}\left(\theta-\theta_{k}\right)+\frac{1}{2}\left(\theta-\theta_{k}\right)^{T} \mathbb{H}_{k}\left(\theta-\theta_{k}\right)
$$

differentiating and equating to zero to solve for $\theta_{k+1}$.

## Learning Parameters

Now assume:

$$
\begin{gathered}
g(\theta)=\sum_{i=1}^{n}\left[\sigma_{\theta}\left(x_{i}\right)-y_{i}\right] x_{i}^{j}=\mathbf{X}^{\top}\left(\sigma_{\theta}(\mathbf{X})-\mathbf{y}\right) \\
\pi_{i}=\sigma_{\theta}\left(x_{i}\right)
\end{gathered}
$$

Let $\mathbb{H}$ represent the Hessian of $J(\theta)$

$$
\begin{aligned}
\mathbb{H}=\frac{\partial}{\partial \theta} g(\theta) & =\frac{\partial}{\partial \theta} \sum_{i=1}^{n}\left[\sigma_{\theta}\left(x_{i}\right)-y_{i}\right] x_{i}^{j} \\
& =\sum_{i=1}^{n}\left[\frac{\partial}{\partial \theta} \sigma_{\theta}\left(x_{i}\right) x_{i}^{j}-\frac{\partial}{\partial \theta} y_{i} x_{i}^{j}\right] \\
& =\sum_{i=1}^{n} \sigma_{\theta}\left(x_{i}\right)\left(1-\sigma_{\theta}\left(x_{i}\right)\right) x_{i} x_{i}^{T} \\
& =\mathbf{X}^{\top} \operatorname{diag}\left(\sigma_{\theta}\left(x_{i}\right)\left(1-\sigma_{\theta}\left(x_{i}\right)\right)\right) \mathbf{X}
\end{aligned}
$$

## Iteratively reweighted least squares (IRLS)

For binary logistic regression, recall that the gradient and Hessian of the negative log-likelihood are given by:

$$
\begin{aligned}
g(\theta)_{k} & =\mathbf{X}^{\boldsymbol{\top}}\left(\pi_{\mathbf{k}}-\mathbf{y}\right) \\
\mathbf{H}_{k} & =\mathbf{X}^{T} S_{k} \mathbf{X} \\
\mathbf{S}_{k} & =\operatorname{diag}\left(\pi_{1 k}\left(1-\pi_{1 k}\right), \ldots, \pi_{n k}\left(1-\pi_{n k}\right)\right) \\
\pi_{i k} & =\operatorname{sigm}\left(\mathbf{x}_{\mathbf{i}} \theta_{\mathbf{k}}\right)
\end{aligned}
$$

The Newton update at iteraion $k+1$ for this model is as follows:

$$
\begin{aligned}
\theta_{k+1} & =\theta_{k}-\mathbb{H}^{-1} g_{k} \\
& =\theta_{k}+\left(X^{T} S_{k} X\right)^{-1} X^{T}\left(y-\pi_{k}\right) \\
& =\left(X^{T} S_{k} X\right)^{-1}\left[\left(X^{T} S_{k} X\right) \theta_{k}+X^{T}\left(y-\pi_{k}\right)\right] \\
& =\left(X^{T} S_{k} X\right)^{-1} X^{T}\left[S_{k} X \theta_{k}+y-\pi_{k}\right]
\end{aligned}
$$

## Regularized Logistic Regression

Unregularised:

$$
J_{1}(\theta)=-\left\{\sum_{i=1}^{n} y_{i} \log \left(\sigma_{\theta}\left(x_{i}\right)\right)+\left(1-y_{i}\right) \log \left(1-\sigma_{\theta}\left(x_{i}\right)\right)\right\}
$$

L2 Regularization:

$$
J(\theta)=J_{1}(\theta)+\lambda \theta^{T} \theta
$$

L1 Regularization:

$$
J(\theta)=J_{1}(\theta)+\lambda|\theta|
$$

