

Bayes Rule.

$$P(A|B)P(B) = P(B|A)P(A)$$

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$

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A = Parameters (θ)

B = Data (D)

$$P(\theta|D) = \frac{P(D|\theta)P(\theta)}{P(D)}$$

← LIKELIHOOD

← EVIDENCE

PRIOR

PROBABILITY

(like Gaussian with mean 0)

POSTERIOR PROBABILITY

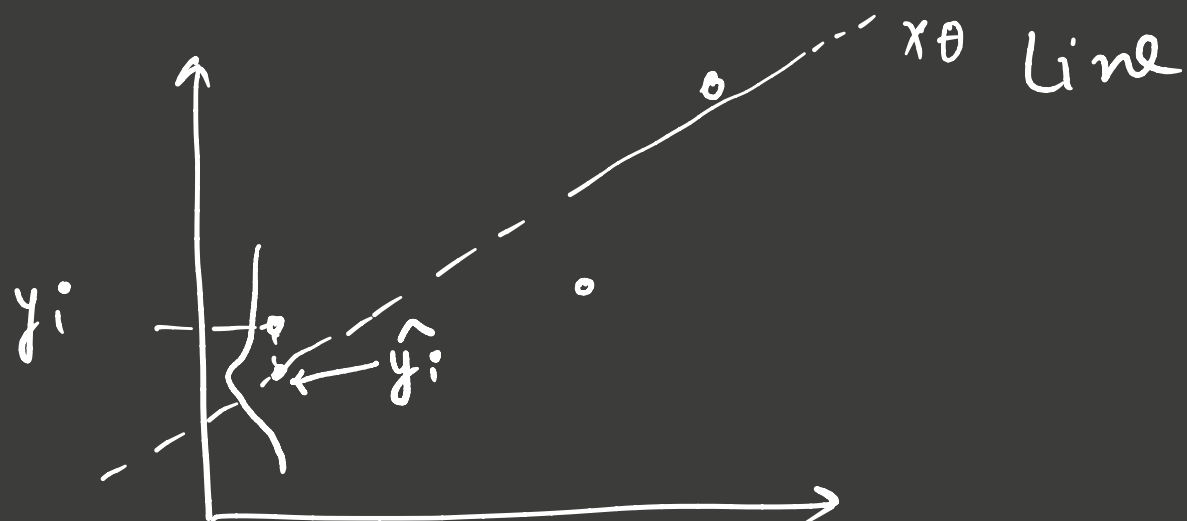
(Prob. after seeing data)

↳ ALSO ACTS AS REGULARIZER

MLE FOR LINEAR REGRESSION

$$\hat{\theta}_{LS} = \underset{\theta}{\operatorname{argmin}} \eta^T \eta = \underset{\theta}{\operatorname{argmin}} (y - X\theta)^T (y - X\theta) \quad \text{LEAST SQUARES SOLN}$$

- ① $\eta_i \sim N(0, \sigma^2)$ (0 MEAN, KNOWN VARIANCE)
- ② η_i INDEPENDENT ACROSS OBSERVATIONS
- ③ $y \sim N(X\theta, \sigma^2) \left\{ X\theta + N(0, \sigma^2) \right\}$



Likelihood = P(Data | Parameters)

Data = $\langle y_i, x_i \rangle$; Parameters = θ, σ

$$P(y | x, \theta, \sigma) = P(y_1 | x_1, \theta, \sigma^2) P(y_2 | x_2, \theta, \sigma^2) \dots$$

$$= \prod_{i=1}^n P(y_i | x_i, \theta, \sigma^2)$$

$$= \prod_{i=1}^n \left(\frac{1}{\sqrt{2\pi\sigma^2}} \right)^n e^{-\frac{1}{2\sigma^2} (y_i - x_i \theta)^2}$$

$$\text{Log Likelihood} = \sum_{i=1}^n \text{Constant} * (y_i - x_i \theta)^2 = \text{Constant} * \sum_{i=1}^n \epsilon_{y_i}^2$$

$$\hat{\theta}_{MLE} = \underset{\theta}{\text{arg max}} (y - X\theta)^T (y - X\theta) = \hat{\theta}_{LS}$$

UNDER NORMALLY DISTRIBUTED
RESIDUAL

MAP FOR LINEAR REGRESSION

- ① $y_i \sim N(0, \sigma^2)$
- ② y_i is independent across observations
- ③ $y \sim N(X\theta, \sigma^2)$
- ④ θ has Gaussian prior i.e. $\theta \sim N(0, \tau^{-2} I)$ Identity

$$P(\theta|D) \propto P(D|\theta) P(\theta) \Rightarrow \log P(\theta|D) \propto \log P(D|\theta) + \log P(\theta)$$

$$\hat{\theta}_{\text{MAP}} = \underset{\theta}{\text{arg max}} \{ \log P(D|\theta) + \log P(\theta) \}$$

$$= \underset{\theta}{\text{arg min}} (y - X\theta)^T (y - X\theta) + \lambda \theta^T \theta$$

MAP with GAUSSIAN PRIOR \Rightarrow
RIDGE REGRESSION

PRIOR $\xRightarrow{\text{LEADS TO}}$ REGULARIZATION

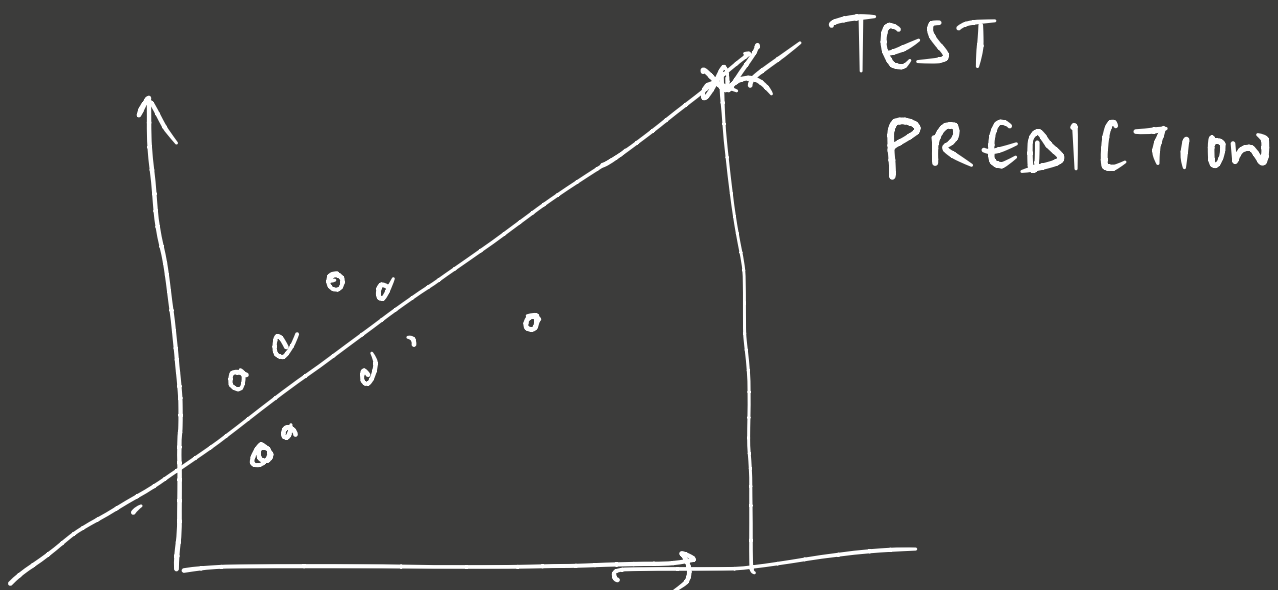
$\theta \sim N(0, \tau^2 I)$: RIDGE REGRESSION

$\theta_i \sim \text{LAPLACE}(0, t)$: LASSO

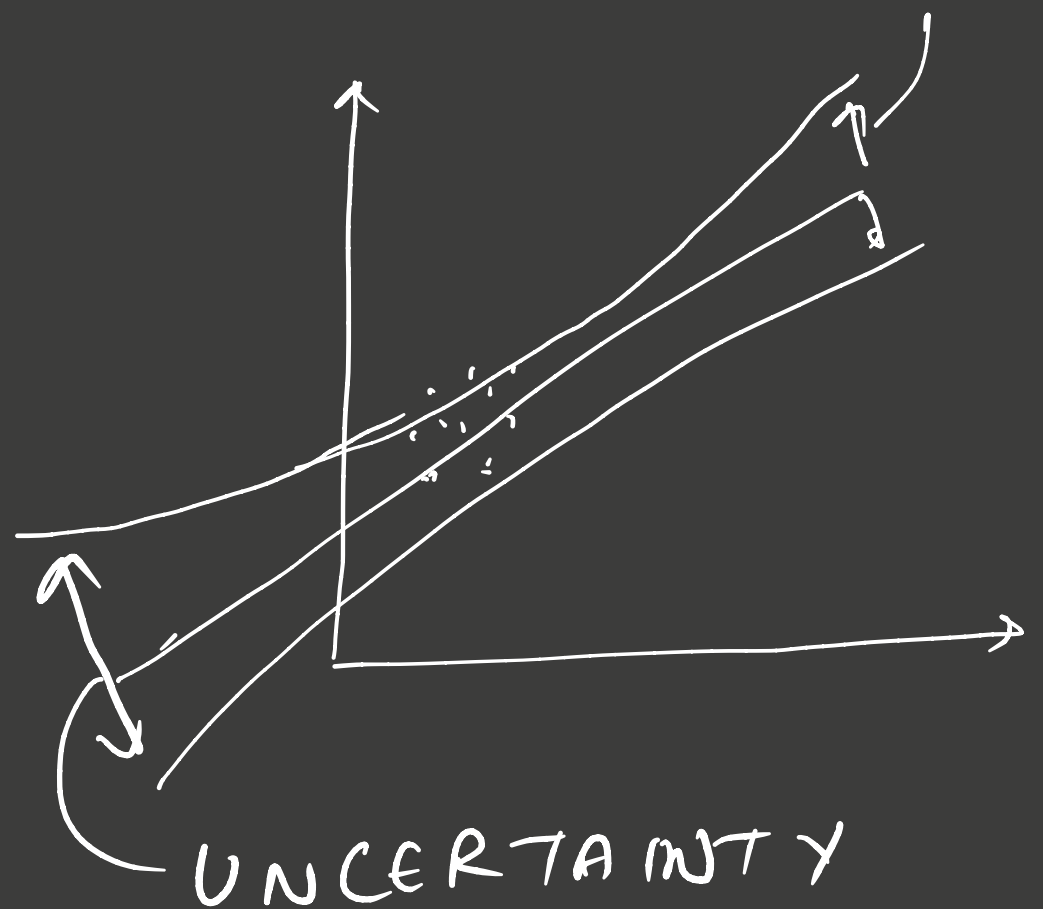
BAYESIAN LINEAR REGRESSION

* POINT ESTIMATE \rightarrow NO MEASURE OF UNCERTAINTY

NON "FULLY"
BAYESIAN
(MAP; MLE)



"FULLY" BAYESIAN



Q: what is $P(y^* | x^*, D)$

$$y_i \sim N(x_i \theta, \sigma^2) \quad \text{where } x_i \in \mathbb{R}^d$$

UNIVARIATE

$$\theta \sim N(0, b^{-1} I)$$

MULTIVARIATE

$$a, b > 0$$

ASSUMPTION

a, b are KNOWN

$$p(D|\theta) \propto \frac{e^{-a/2 (y-x\theta)^T (y-x\theta)}}{e} \quad \{\text{likelihood}\}$$

$$p(\theta|D) \propto p(D|\theta) p(\theta)$$

$$\propto \frac{e^{-a/2 (y-x\theta)^T (y-x\theta)}}{e} \cdot \frac{e^{-b/2 \theta^T \theta}}{e}$$

$$\propto e^{-a/2 (y-x\theta)^T (y-x\theta) - b/2 \theta^T \theta}$$

$$\text{Let } z = a (y-x\theta)^T (y-x\theta) + b \theta^T \theta$$

$$= a y^T y - 2a \theta^T x^T y + \theta^T (a x^T x + b I) \theta$$

$$\text{Let } z = (\theta - \mu)^T \Lambda (\theta - \mu)$$

$$\theta^T \Lambda \theta - 2\theta^T \Lambda \mu + \text{constant} = a y^T y - 2a \theta^T x^T y + \theta^T (a x^T x + b I) \theta$$

$$\Rightarrow \Lambda = a X^T X + b I$$

$$\text{and } \mu = a \Lambda^{-1} X^T y$$

$$p(\theta | D) \sim N(\theta | \mu, \Lambda^{-1})$$

NOW WE WANT

$p(y^* | x^*, D, a, b)$ Predictive distribution,
 \searrow (x^*, y^*) new point

USE ALL θ

$$p(y^* | x^*, D, a, b) = \int p(y^* | \theta, x^*, a) p(\theta | D, a, b) d\theta$$

$$= \int N(y^* | x^* \theta, \sigma^{-1}) N(\theta | \mu, \bar{\sigma}^{-1}) d\theta$$

$$\propto e^{-\frac{\lambda}{2} (y^* - x^* \theta)^2 - \frac{1}{2} (\theta - \mu)^T \Lambda (\theta - \mu)} d\theta$$

↑
F

$$F = (\theta - \mu)^T L (\theta - \mu)$$

$$= \theta^T (a x^* x^{*T} + \Lambda) \theta - 2 \theta^T (x^* y^* a + \Lambda \mu) + a y^{*2}$$

$$L = a x^* x^{*T} + \Lambda$$

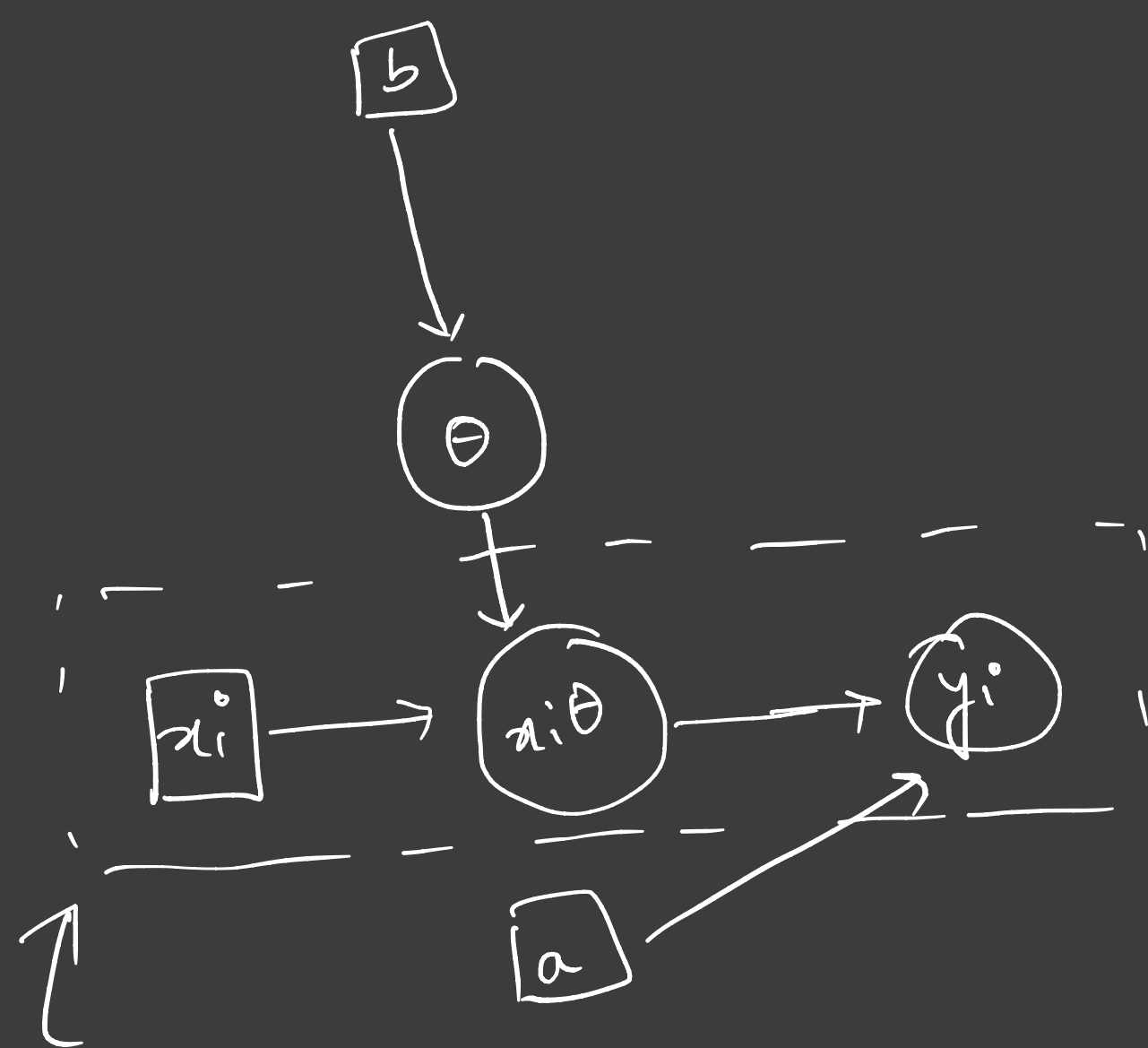
$$m = L^{-1} (a y^* x^* + \Lambda \mu)$$

⋮

$$P(y^* | x^*, D) = N(y^* | u, \frac{1}{\lambda})$$

$$u = \mu^T x^*$$

$$\frac{1}{\lambda} = \frac{1}{a} + x^{*T} \Lambda x^*$$



GRAPHICAL
MODEL
FOR
BAYESIAN
LINEAR
REGRESSION

Plate
model.
(repeated
over time i)