# **Logistic Regression**

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Aim: Probability(Orange | Radius) ? or





 $P(y = Orange | Radius = r) = \theta_0 + \theta_1 \times r$ 



$$P(y = Orange | Radius = r) = heta_0 + heta_1 imes r$$

Generally,

$$P(y=1|x)=x^{T}\theta$$



$$\mathsf{P}(y = \mathit{Orange} | \mathit{Radius} = r) = heta_0 + heta_1 imes r$$

Generally,

$$P(y=1|x) = x^T \theta$$

For N examples

$$\mathsf{P}(\mathbf{y}=1|X)=X heta$$

3

Prediction: If  $\theta_0 + \theta_1 \times Radius > 0.5 \rightarrow \text{Orange}$ Else  $\rightarrow$  Tomato Problem: Range of  $X\theta$  is  $(-\infty, \infty)$ But  $P(y = 1 | ...) \in [0, 1]$ 





Linear regression for classification gives a poor prediction!

## Ideal boundary



• Have a decision function similar to the above (but not so sharp and discontinuous)

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- Have a decision function similar to the above (but not so sharp and discontinuous)
- Aim: use linear regression still!



Question. Can we still use Linear Regression? Answer. Yes! Transform  $x^T \theta \rightarrow [0, 1]$ 



 $z \to \infty$ 

 $z \to \infty$  $\sigma(z) \to 1$   $z \to \infty$  $\sigma(z) \to 1$  $z \to -\infty$   $egin{aligned} z &
ightarrow \infty \ \sigma(z) &
ightarrow 1 \ z &
ightarrow -\infty \ \sigma(z) &
ightarrow 0 \end{aligned}$ 

 $z \to \infty$   $\sigma(z) \to 1$   $z \to -\infty$   $\sigma(z) \to 0$ z = 0  $egin{aligned} z o \infty \ \sigma(z) o 1 \ z o -\infty \ \sigma(z) o 0 \ z = 0 \ \sigma(z) = 0.5 \end{aligned}$ 

## Question. Could you use some other transformation ( $\phi$ ) of $x^T \theta$ s.t.

$$\phi(x^{\mathsf{T}}\theta) \in [0,1]$$

Yes! But Logistic Regression works.

$$P(y=1|X) = \sigma(X\theta) = \frac{1}{1+e^{-X\theta}}$$

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$$\therefore \frac{P(y=1|X)}{1-P(y=1|X)} = e^{X\theta} \implies X\theta = \log \frac{P(y=1|X)}{1-P(y=1|X)}$$

 $\frac{P(win)}{P(loss)}$ 

Here,

$$Odds = \frac{P(y=1)}{P(y=0)}$$
  
logits = log-odds = log  $\frac{P(y=1)}{P(y=0)} = X\theta$ 



## Logits Usage

Computes the cross-entropy loss between true labels and predicted labels.				
Inherits From: Loss				
View aliases				
<pre>tf.keras.losses.BinaryGrossentropy(     from_logits=False,     label_emothing=0.6,     axis=-1,     reduction=losse_utils.ReductionV2.AVT0,     name='binary_crossentropy' )</pre>		0		
Used in the notebooks				
Used in the guide	Used in the tutorials			
The Functional API	Load a pandas DataFrame			
Transfer learning and fine-tuning	Transfer learning and fine-tuning			
<ul> <li>Distributed training with TensorFlow</li> </ul>	Basic text classification			
Estimators	Warm-start embedding layer matrix			
Making new Layers and Models via subclassing	Parameter server training with ParameterServerStrategy			
Use this cross-entropy loss for binary (0 or 1) classification applications. The loss function requires the following inputs:				

- y\_true (true label): This is either 0 or 1.
- y\_pred (predicted value): This is the model's prediction, i.e. a single floating-point value which either represents a logit, (i.e. value in [inf, inf] when from\_logits=True) or a probability (i.e. value in [0, 1] when from\_logits=False).

Recommended Usage: (set from\_logits=True )

## Logits Usage

TensorFlow > Resources > Proba	ability > API	Was this helpful?	ம	<b>P</b>	
tfp.distribution	s.Bernoulli 🛛 -				
View source on GitHub					
Bernoulli distribution.					
Inherits From: Distribution	AutoCompositeTensor				
<pre>tfp.distributions.Bernoul logits=None, probs=None, dtype=tf.int32, validate_args=False, allow_nan_stats=True, name='Bernoulli' )</pre>	11(		Ð		
The Bernoulli distribution with probs parameter, i.e., the probability of a 1 outcome (vs a 6 outcome).					
Args					
logits	An N-D Tensor representing the log-odds of a 1 event. Each entry in the Tensor parameterizes an independent Bernoulli distribution where the probability of an event is sigmoid(logits). Only one of logits or probs should be passed in.				
probs	An N-D Tensor representing the probability of a 1 event. Each entry in the Tensor parameterizes an independent Bernoulli distribution. Only one of logits or probs should be passed in.				

Q. What is decision boundary for Logistic Regression?

Q. What is decision boundary for Logistic Regression? Decision Boundary: P(y = 1|X) = P(y = 0|X)

or 
$$\frac{1}{1+e^{-X\theta}} = \frac{e^{-X\theta}}{1+e^{-X\theta}}$$
  
or  $e^{X\theta} = 1$   
or  $X\theta = 0$ 

Notebook: https://nipunbatra.github.io/ml2023/notebooks/posts/logistic.html Could we use cost function as:

$$J(\theta) = \sum (y_i - \hat{y}_i)^2$$
$$\hat{y}_i = \sigma(X\theta)$$

Answer: No (Non-Convex) (See Jupyter Notebook)

#### Cost function convexity



 $17 \\ 16 \\ 15 \\ 14 \\ 13 \\ 12 \\ 11 \\ 10$ 

Likelihood = 
$$P(D|\theta)$$
  
 $P(y|X, \theta) = \prod_{i=1}^{n} P(y_i|x_i, \theta)$   
where y = 0 or 1
Likelihood = 
$$P(D|\theta)$$
  
 $P(y|X, \theta) = \prod_{i=1}^{n} P(y_i|x_i, \theta)$   
 $= \prod_{i=1}^{n} \left\{ \frac{1}{1 + e^{-x_i^T \theta}} \right\}^{y_i} \left\{ 1 - \frac{1}{1 + e^{-x_i^T \theta}} \right\}^{1-y_i}$ 

[Above: Similar to  $P(D|\theta)$  for Linear Regression;

Difference Bernoulli instead of Gaussian]

 $-\log P(y|X, \theta) =$  Negative Log Likelihood = Cost function will be minimising =  $J(\theta)$ 

#### Likelihood Visualisation



• Assume you have a coin and flip it ten times and get (H, H, T, T, T, H, H, T, T, T).

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- Idea find MLE estimate for  $\boldsymbol{\theta}$

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- Verify the above: if x = 0 (Tails),  $P(D_1 = x|\theta) = 1 \theta$  and if x = 1 (Heads),  $P(D_1 = x|\theta) = \theta$

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$$\frac{\partial \mathcal{LL}(\theta)}{\partial \theta} = 0 \implies \frac{n_h}{\theta} + \frac{n_t}{1-\theta} = 0 \implies \theta_{MLE} = \frac{n_h}{n_h + n_t}$$

$$J(\theta) = -\log\left\{\prod_{i=1}^{n}\left\{\frac{1}{1+e^{-x_i^T\theta}}\right\}^{y_i}\left\{1-\frac{1}{1+e^{-x_i^T\theta}}\right\}^{1-y_i}\right\}$$
$$J(\theta) = -\left\{\sum_{i=1}^{n}y_i\log(\sigma_\theta(x_i)) + (1-y_i)\log(1-\sigma_\theta(x_i))\right\}$$

$$\begin{split} J(\theta) &= -\log\left\{\prod_{i=1}^{n}\left\{\frac{1}{1+e^{-x_i^T\theta}}\right\}^{y_i}\left\{1-\frac{1}{1+e^{-x_i^T\theta}}\right\}^{1-y_i}\right\}\\ J(\theta) &= -\left\{\sum_{i=1}^{n}y_i\log(\sigma_\theta(x_i)) + (1-y_i)\log(1-\sigma_\theta(x_i))\right\} \end{split}$$

This cost function is called cross-entropy.

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Why?

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Let us try to write the cost function for a single example:

$$J(\theta) = -y_i \log \hat{y}_i - (1 - y_i) \log(1 - \hat{y}_i)$$

First, assume  $y_i$  is 0, then if  $\hat{y}_i$  is 0, the loss is 0; but, if  $\hat{y}_i$  is 1, the loss tends towards infinity!



What is the interpretation of the cost function?

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$$J(\theta) = -y_i \log \hat{y}_i - (1 - y_i) \log(1 - \hat{y}_i)$$

Now, assume  $y_i$  is 1, then if  $\hat{y}_i$  is 0, the loss is huge; but, if  $\hat{y}_i$  is 1, the loss is zero!



#### Cost function convexity





$$\begin{split} \frac{\partial J(\theta)}{\partial \theta_j} &= -\frac{\partial}{\partial \theta_j} \bigg\{ \sum_{i=1}^n y_i log(\sigma_\theta(x_i)) + (1 - y_i) log(1 - \sigma_\theta(x_i)) \bigg\} \\ &= -\sum_{i=1}^n \bigg[ y_i \frac{\partial}{\partial \theta_j} \log(\sigma_\theta(x_i)) + (1 - y_i) \frac{\partial}{\partial \theta_j} log(1 - \sigma_\theta(x_i)) \bigg] \end{split}$$

$$\frac{\partial J(\theta)}{\partial \theta_j} = -\sum_{i=1}^n \left[ y_i \frac{\partial}{\partial \theta_j} \log(\sigma_{\theta}(x_i)) + (1 - y_i) \frac{\partial}{\partial \theta_j} \log(1 - \sigma_{\theta}(x_i)) \right]$$

$$= -\sum_{i=1}^{n} \left[ \frac{y_i}{\sigma_{\theta}(x_i)} \frac{\partial}{\partial \theta_j} \sigma_{\theta}(x_i) + \frac{1 - y_i}{1 - \sigma_{\theta}(x_i)} \frac{\partial}{\partial \theta_j} (1 - \sigma_{\theta}(x_i)) \right] \quad (1)$$

Aside:

$$\frac{\partial}{\partial z}\sigma(z) = \frac{\partial}{\partial z}\frac{1}{1+e^{-z}} = -(1+e^{-z})^{-2}\frac{\partial}{\partial z}(1+e^{-z})$$
$$= \frac{e^{-z}}{(1+e^{-z})^2} = \left(\frac{1}{1+e^{-z}}\right)\left(\frac{e^{-z}}{1+e^{-z}}\right) = \sigma(z)\left\{\frac{1+e^{-z}}{1+e^{-z}} - \frac{1}{1+e^{-z}}\right\}$$
$$= \sigma(z)(1-\sigma(z))$$

Resuming from (1)  

$$\frac{\partial J(\theta)}{\partial \theta_{j}} = -\sum_{i=1}^{n} \left[ \frac{y_{i}}{\sigma_{\theta}(x_{i})} \frac{\partial}{\partial \theta_{j}} \sigma_{\theta}(x_{i}) + \frac{1 - y_{i}}{1 - \sigma_{\theta}(x_{i})} \frac{\partial}{\partial \theta_{j}} (1 - \sigma_{\theta}(x_{i})) \right]$$

$$= -\sum_{i=1}^{n} \left[ \frac{y_{i} \sigma_{\theta}(x_{i})}{\sigma_{\theta}(x_{i})} (1 - \sigma_{\theta}(x_{i})) \frac{\partial}{\partial \theta_{j}} (x_{i}^{T} \theta) + \frac{1 - y_{i}}{1 - \sigma_{\theta}(x_{i})} (1 - \sigma_{\theta}(x_{i})) \frac{\partial}{\partial \theta_{j}} (1 - \sigma_{\theta}(x_{i})) \right]$$

$$= -\sum_{i=1}^{n} \left[ y_{i} (1 - \sigma_{\theta}(x_{i})) x_{i}^{j} - (1 - y_{i}) \sigma_{\theta}(x_{i}) x_{i}^{j} \right]$$

$$= -\sum_{i=1}^{n} \left[ (y_{i} - y_{i} \sigma_{\theta}(x_{i}) - \sigma_{\theta}(x_{i}) + y_{i} \sigma_{\theta}(x_{i})) x_{i}^{j} \right]$$

$$= \sum_{i=1}^{n} \left[ \sigma_{\theta}(x_{i}) - y_{i} \right] x_{i}^{j}$$

$$\frac{\frac{\partial J(\theta)}{\theta_j} = \sum_{i=1}^{N} \left[ \sigma_{\theta}(x_i) - y_i \right] x_i^j}{\left[ \frac{\partial J(\theta)}{\theta_j} = \sum_{i=1}^{N} \left[ \hat{y}_i - y_i \right] x_i^j \right]}$$

Now, just use Gradient Descent!

 $\frac{\partial J(B)}{\partial J(B)} = \sum_{i=1}^{N} (\hat{y_i} - \hat{y_i}) z_i^{j}$ 201

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 $= \sum_{i=1}^{N} (\hat{y_{i}} - \hat{y_{i}}) z_{i}^{j} = x_{1\times N}^{J} (\hat{y_{i}} - \hat{y_{i}})$ 9](b) 20j (ý-y) J10) ٥Ð (x - x) 92(B) x<sup>o<sup>T</sup> (y<sup>°</sup> - y)</sup> 92(0)

 $\sum_{i=1}^{N} (\hat{y_i} - \hat{y_i}) z_i^j = \frac{x_i^j}{x_{1xN}} (\hat{y} - \hat{y})$ 9](b) 20j (ý-y) JJ10) 0Di (K- <sup>2</sup> K 19-4) 9200) x<sup>pT</sup> (y<sup>-</sup>-y) 92(0)



What happens if you apply logistic regression on the above data?



Linear boundary will not be accurate here. What is the technical name of the problem?



Linear boundary will not be accurate here. What is the technical name of the problem? Bias!

$$\phi(x) = \begin{bmatrix} \phi_0(x) \\ \phi_1(x) \\ \vdots \\ \phi_{K-1}(x) \end{bmatrix} = \begin{bmatrix} 1 \\ x \\ x^2 \\ x^3 \\ \vdots \\ x^{K-1} \end{bmatrix} \in \mathbb{R}^K$$



Using  $x_1^2, x_2^2$  as additional features, we are able to learn a more accurate classifier.

How would you expect the probability contours look like?

How would you expect the probability contours look like?







How would you learn a classifier? Or, how would you expect the classifier to learn decision boundaries?





- 1. Use one-vs.-all on Binary Logistic Regression
- 2. Use one-vs.-one on Binary Logistic Regression
- 3. Extend <u>Binary</u> Logistic Regression to <u>Multi-Class</u> Logistic Regression





- 1. Learn P(setosa (class 1)) =  $\mathcal{F}(X\theta_1)$
- 2. P(versicolor (class 2)) =  $\mathcal{F}(X\theta_2)$
- 3. P(virginica (class 3)) =  $\mathcal{F}(X\theta_3)$
- 4. Goal: Learn  $\theta_i \forall i \in \{1, 2, 3\}$
- 5. Question: What could be an  $\mathcal{F}$ ?





- 1. Question: What could be an  $\mathcal{F}$ ?
- 2. Property:  $\sum_{i=1}^{3} \mathcal{F}(X\theta_i) = 1$
- 3. Also  $\mathcal{F}(z) \in [0,1]$
- 4. Also,  $\mathcal{F}(z)$  has squashing proprties:  $R\mapsto [0,1]$

$$egin{aligned} Z \in \mathbb{R}^d \ \mathcal{F}(z_i) &= rac{e^{z_i}}{\sum_{i=1}^d e^{z_i}} \ dots & \sum \mathcal{F}(z_i) = 1 \end{aligned}$$

 $\mathcal{F}(z_i)$  refers to probability of class  $\underline{i}$ 

# Softmax for Multi-Class Logistic Regression

$$k = \{1, \dots, K\} \text{classes}$$
$$\theta = \begin{bmatrix} \vdots & \vdots & \vdots & \vdots \\ \theta_1 & \theta_2 & \cdots & \theta_K \\ \vdots & \vdots & \vdots & \vdots \end{bmatrix}$$
$$\hat{y}^k = P(y = k | X, \theta) = \frac{e^{X\theta_k}}{\sum_{k=1}^K e^{X\theta_k}}$$

#### Softmax for Multi-Class Logistic Regression

For K = 2 classes,

$$P(y = k | X, \theta) = \frac{e^{X\theta_k}}{\sum_{k=1}^{K} e^{X\theta_k}}$$
$$P(y = 0 | X, \theta) = \frac{e^{X\theta_0}}{e^{X\theta_0} + e^{X\theta_1}}$$
$$P(y = 1 | X, \theta) = \frac{e^{X\theta_1}}{e^{X\theta_0} + e^{X\theta_1}} = \frac{e^{X\theta_1}}{e^{X\theta_1}\{1 + e^{X(\theta_0 - \theta_1)}\}}$$
$$= \frac{1}{1 + e^{-X\theta'}}$$
$$= \text{Sigmoid!}$$

Assume our prediction and ground truth for the three classes for  $i^{th}$  point is:

$$\hat{y}_{i} = \begin{bmatrix} 0.1\\0.8\\0.1 \end{bmatrix} = \begin{bmatrix} \hat{y}_{i}^{1}\\\hat{y}_{i}^{2}\\\hat{y}_{i}^{3} \end{bmatrix}$$
$$y_{i} = \begin{bmatrix} 0\\1\\0 \end{bmatrix} = \begin{bmatrix} y_{i}^{1}\\y_{i}^{2}\\y_{i}^{3} \end{bmatrix}$$

meaning the true class is Class #2

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Let us calculate  $-\sum_{k=1}^{3} y_{i}^{k} \log \hat{y}_{i}^{k}$ 

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meaning the true class is Class #2

Let us calculate  $-\sum_{k=1}^{3} y_{i}^{k} \log \hat{y}_{i}^{k}$ 

 $= -(0\times \log(0.1) + 1\times \log(0.8) + 0\times \log(0.1))$ 

Assume our prediction and ground truth for the three classes for  $i^{th}$  point is:

$$\hat{y}_i = \begin{bmatrix} 0.1\\ 0.8\\ 0.1 \end{bmatrix} = \begin{bmatrix} \hat{y}_i^1\\ \hat{y}_i^2\\ \hat{y}_i^3 \end{bmatrix}$$
$$y_i = \begin{bmatrix} 0\\ 1\\ 0 \end{bmatrix} = \begin{bmatrix} y_i^1\\ y_i^2\\ y_i^3 \end{bmatrix}$$

meaning the true class is Class #2

Let us calculate 
$$-\sum_{k=1}^{3} y_{i}^{k} \log \hat{y}_{i}^{k}$$

$$= -(0 \times \log(0.1) + 1 \times \log(0.8) + 0 \times \log(0.1))$$

Tends to zero

Assume our prediction and ground truth for the three classes for  $i^{th}$  point is:

$$\hat{y}_{i} = \begin{bmatrix} 0.3\\ 0.4\\ 0.3 \end{bmatrix} = \begin{bmatrix} \hat{y}_{i}^{1}\\ \hat{y}_{i}^{2}\\ \hat{y}_{i}^{3} \end{bmatrix}$$
$$y_{i} = \begin{bmatrix} 0\\ 1\\ 0 \end{bmatrix} = \begin{bmatrix} y_{i}^{1}\\ y_{i}^{2}\\ y_{i}^{3} \end{bmatrix}$$

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Let us calculate  $-\sum_{k=1}^{3} y_{i}^{k} \log \hat{y}_{i}^{k}$ 

 $= -(0\times \log(0.1) + 1\times \log(0.4) + 0\times \log(0.1))$ 

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Let us calculate  $-\sum_{k=1}^{3} y_{i}^{k} \log \hat{y}_{i}^{k}$ 

 $= -(0 \times \log(0.1) + 1 \times \log(0.4) + 0 \times \log(0.1))$ 

High number! Huge penalty for misclassification!

For 2 class we had:

$$J(\theta) = -\left\{\sum_{i=1}^{n} y_i \log(\sigma_{\theta}(x_i)) + (1 - y_i) \log(1 - \sigma_{\theta}(x_i))\right\}$$

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More generally,

For 2 class we had:

$$J(\theta) = -\left\{\sum_{i=1}^{n} y_i \log(\sigma_{\theta}(x_i)) + (1 - y_i) \log(1 - \sigma_{\theta}(x_i))\right\}$$

More generally,

$$J( heta) = -\left\{\sum_{i=1}^n y_i \log(\hat{y}_i) + (1-y_i)\log(1-\hat{y}_i)
ight\}$$

Extend to K-class:

$$J(\theta) = -\left\{\sum_{i=1}^{n}\sum_{k=1}^{K}y_{i}^{k}\log(\hat{y}_{i}^{k})\right\}$$

$$J(\theta) = -\left\{\sum_{i=1}^{n}\sum_{k=1}^{K}y_{i}^{k}\log(\hat{y}_{i}^{k})\right\}$$

$$\nabla_{\theta k} J(\theta) = \sum_{i=1}^{N} (\hat{y}_i^k - y_i^k) x_i$$
The Hessian matrix of f(.) with respect to  $\theta$ , written  $\nabla_{\theta}^2 f(\theta)$  or simply as  $\mathbb{H}$ , is the  $d \times d$  matrix of partial derivatives,



The most basic second-order optimization algorithm is Newton's algorithm, which consists of updates of the form,

$$\theta_{k+1} = \theta_k - \mathbb{H}_k^1 g_k$$

where  $g_k$  is the gradient at step k. This algorithm is derived by making a second-order Taylor series approximation of  $f(\theta)$  around  $\theta_k$ :

$$f_{quad}(\theta) = f(\theta_k) + g_k^T(\theta - \theta_k) + \frac{1}{2}(\theta - \theta_k)^T \mathbb{H}_k(\theta - \theta_k)$$

differentiating and equating to zero to solve for  $\theta_{k+1}$ .

## **Learning Parameters**

Now assume:

$$g(\theta) = \sum_{i=1}^{n} \left[ \sigma_{\theta}(x_i) - y_i \right] x_i^j = \mathbf{X}^{\mathsf{T}} (\sigma_{\theta}(\mathbf{X}) - \mathbf{y})$$
$$\pi_i = \sigma_{\theta}(x_i)$$

Let  $\mathbb{H}$  represent the Hessian of  $J(\theta)$ 

$$\mathbb{H} = \frac{\partial}{\partial \theta} g(\theta) = \frac{\partial}{\partial \theta} \sum_{i=1}^{n} \left[ \sigma_{\theta}(x_{i}) - y_{i} \right] x_{i}^{j}$$
$$= \sum_{i=1}^{n} \left[ \frac{\partial}{\partial \theta} \sigma_{\theta}(x_{i}) x_{i}^{j} - \frac{\partial}{\partial \theta} y_{i} x_{i}^{j} \right]$$
$$= \sum_{i=1}^{n} \sigma_{\theta}(x_{i}) (1 - \sigma_{\theta}(x_{i})) x_{i} x_{i}^{T}$$
$$= \mathbf{X}^{\mathsf{T}} diag(\sigma_{\theta}(x_{i}) (1 - \sigma_{\theta}(x_{i}))) \mathbf{X}$$

## Iteratively reweighted least squares (IRLS)

For binary logistic regression, recall that the gradient and Hessian of the negative log-likelihood are given by:

$$g(\theta)_{k} = \mathbf{X}^{\mathsf{T}}(\pi_{\mathbf{k}} - \mathbf{y})$$
$$\mathbf{H}_{k} = \mathbf{X}^{\mathsf{T}}S_{k}\mathbf{X}$$
$$\mathbf{S}_{k} = diag(\pi_{1k}(1 - \pi_{1k}), \dots, \pi_{nk}(1 - \pi_{nk}))$$
$$\pi_{ik} = sigm(\mathbf{x}_{i}\theta_{\mathbf{k}})$$

The Newton update at iteraion k + 1 for this model is as follows:

$$\begin{aligned} \theta_{k+1} &= \theta_k - \mathbb{H}^{-1} g_k \\ &= \theta_k + (X^T S_k X)^{-1} X^T (y - \pi_k) \\ &= (X^T S_k X)^{-1} [(X^T S_k X) \theta_k + X^T (y - \pi_k)] \\ &= (X^T S_k X)^{-1} X^T [S_k X \theta_k + y - \pi_k] \end{aligned}$$

## Unregularised:

$$J_1(\theta) = -\left\{\sum_{i=1}^n y_i \log(\sigma_{\theta}(x_i)) + (1 - y_i) \log(1 - \sigma_{\theta}(x_i))\right\}$$

L2 Regularization:

$$J(\theta) = J_1(\theta) + \lambda \theta^T \theta$$

L1 Regularization:

$$J(\theta) = J_1(\theta) + \lambda |\theta|$$