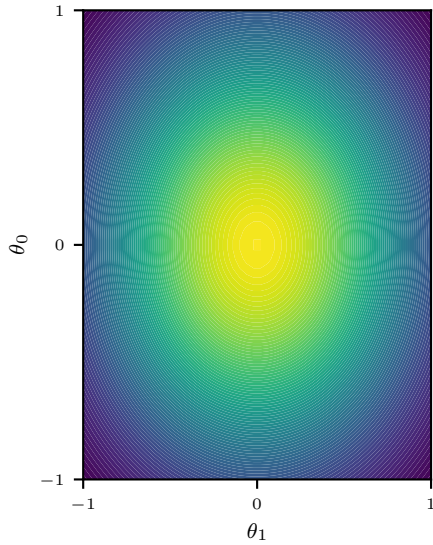
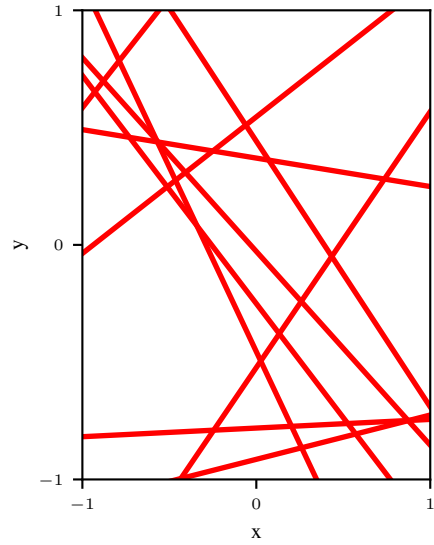


likelihood



prior/posterior



data space